



ลิขสิทธิ์มหาวิทยาลัยเชียงใหม่

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Appendix A

Basic and Auxiliary Results

A.1 Selection of c

During the sliding mode, let

$$s(k) = c \left[x(k) - x_d(k) \right] = 0, \quad (\text{A.1})$$

we obtain

$$\sum_{i=1}^N c_i x_i(k) = \sum_{i=1}^N c_i x_{di}(k), \quad (\text{A.2})$$

applying the Z-transform, we obtain

$$\sum_{i=1}^N c_i X_i(z) = \sum_{i=1}^N c_i X_{di}(z) \quad (\text{A.3})$$

From the system relation

$$x_n(k) = x_{n+1}(k-1) \quad (\text{A.4})$$

for $n = 1, \dots, N-1$. Apply Z-Transformation we obtain

$$\left. \begin{aligned} X_1(z) &= z^{-1} X_2(z) \\ X_2(z) &= z^{-1} X_3(z) \\ &\vdots \\ X_{N-1}(z) &= z^{-1} X_N(z). \end{aligned} \right\} \quad (\text{A.5})$$

or

$$X_i(z) = z^{-(N-i)} X_N(z). \quad (\text{A.6})$$

Then Eq.(A.3) can be rewritten as

$$\sum_{i=1}^N c_i z^{-(N-i)} X_N(z) = \sum_{i=1}^N c_i X_{di}(z)$$

$$X_N(z) = \frac{\sum_{i=1}^N c_i X_{di}(z)}{\sum_{i=1}^N c_i z^{-(N-i)}}.$$

The characteristic equation of this system is

$$\sum_{i=1}^N c_i z^{-(N-i)} = c_N + c_{N-1} z^{-1} + \dots + c_1 z^{-(N-1)} = 0. \quad (\text{A.7})$$

This means the roots of this characteristic equation must be kept inside the unit disk for the system stability.

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