

Appendix A Microcontroller use in this research



dsPIC30F6010A/6015

dsPIC30F6010A/6015 Enhanced Flash 16-bit Digital Signal Controller (DSC)

Note: This data sheet summarizes features of this group of dsPIC30F devices and is not intended to be a complete reference source. For more information on the CPU, peripherals, register descriptions and general device functionality, refer to the "dsPIC30F Family Reference Manual" (DS70046). For more information on the device instruction set and programming, refer to the "dsPIC30F/33F Programmers Reference Manual" (DS70157).

High-Performance Modified RISC CPU:

- Modified Harvard architecture
- C compiler optimized instruction set architecture with flexible Addressing modes
- 83 base instructions
- 24-bit wide instructions, 16-bit wide data path
- 144 Kbytes on-chip Flash program space (Instruction words)
- 8 Kbytes of on-chip data RAM
- 4 Kbytes of nonvolatile data EEPROM
- Up to 30 MIPS operation:
 - DC to 40 MHz external clock input
 - 4 MHz-10 MHz oscillator input with PLL active (4x, 8x, 16x)
 - 7.37 MHz internal RC with PLL active (4x, 8x, 16x)
- 44 interrupt sources:
 - 5 external interrupt sources
 - 8 user selectable priority levels for each interrupt source
 - 4 processor trap sources
- 16 x 16-bit working register array

DSP Engine Features:

- Dual data fetch
- Accumulator write-back for DSP operations
- Modulo and Bit-Reversed Addressing modes
- Two, 40-bit wide accumulators with optional saturation logic
- 17-bit x 17-bit single-cycle hardware fractional/integer multiplier
- All DSP instructions single cycle
- ± 16 -bit single-cycle shift

Peripheral Features:

- High-current sink/source I/O pins: 25 mA/25 mA
- Timer module with programmable prescaler:
 - Five 16-bit timers/counters; optionally pair 16-bit timers into 32-bit timer modules
- 16-bit Capture input functions
- 16-bit Compare/PWM output functions
- 3-wire SPI modules (supports 4 Frame modes)
- I²C™ module supports Multi-Master/Slave mode and 7-bit/10-bit addressing
- 2 UART modules with FIFO Buffers
- 2 CAN modules, 2.0B compliant (dsPIC306010A)
- 1 CAN module, 2.0B compliant (dsPIC306015)

Motor Control PWM Module Features:

- 8 PWM output channels:
 - Complementary or Independent Output modes
 - Edge and Center-Aligned modes
- 4 duty cycle generators
- Dedicated time base
- Programmable output polarity
- Dead-Time control for Complementary mode
- Manual output control
- Trigger for A/D conversions

Quadrature Encoder Interface Module Features:

- Phase A, Phase B and Index Pulse input
- 16-bit up/down position counter
 - Count direction status
 - Position Measurement (x2 and x4) mode
 - Programmable digital noise filters on inputs
 - Alternate 16-bit Timer/Counter mode
 - Interrupt on position counter rollover/underflow

dsPIC30F6010A/6015

Analog Features:

- 10-bit Analog-to-Digital Converter (ADC) with 4 S/H Inputs:
 - 1 Msps conversion rate
 - 16 input channels
 - Conversion available during Sleep and Idle
- Programmable Brown-out Reset

Special Microcontroller Features:

- Enhanced Flash program memory:
 - 10,000 erase/write cycle (min.) for industrial temperature range, 100K (typical)
- Data EEPROM memory:
 - 100,000 erase/write cycle (min.) for industrial temperature range, 1M (typical)
- Self-reprogrammable under software control

- Power-on Reset (POR), Power-up Timer (PWRT) and Oscillator Start-up Timer (OST)
- Flexible Watchdog Timer (WDT) with on-chip, low-power RC oscillator for reliable operation
- Fail-Safe Clock Monitor operation detects clock failure and switches to on-chip, low-power RC oscillator
- Programmable code protection
- In-Circuit Serial Programming™ (ICSP™)
- Selectable Power Management modes
 - Sleep, Idle and Alternate Clock modes

CMOS Technology:

- Low-power, high-speed Flash technology
- Wide operating voltage range (2.5V to 5.5V)
- Industrial and Extended temperature ranges
- Low-power consumption

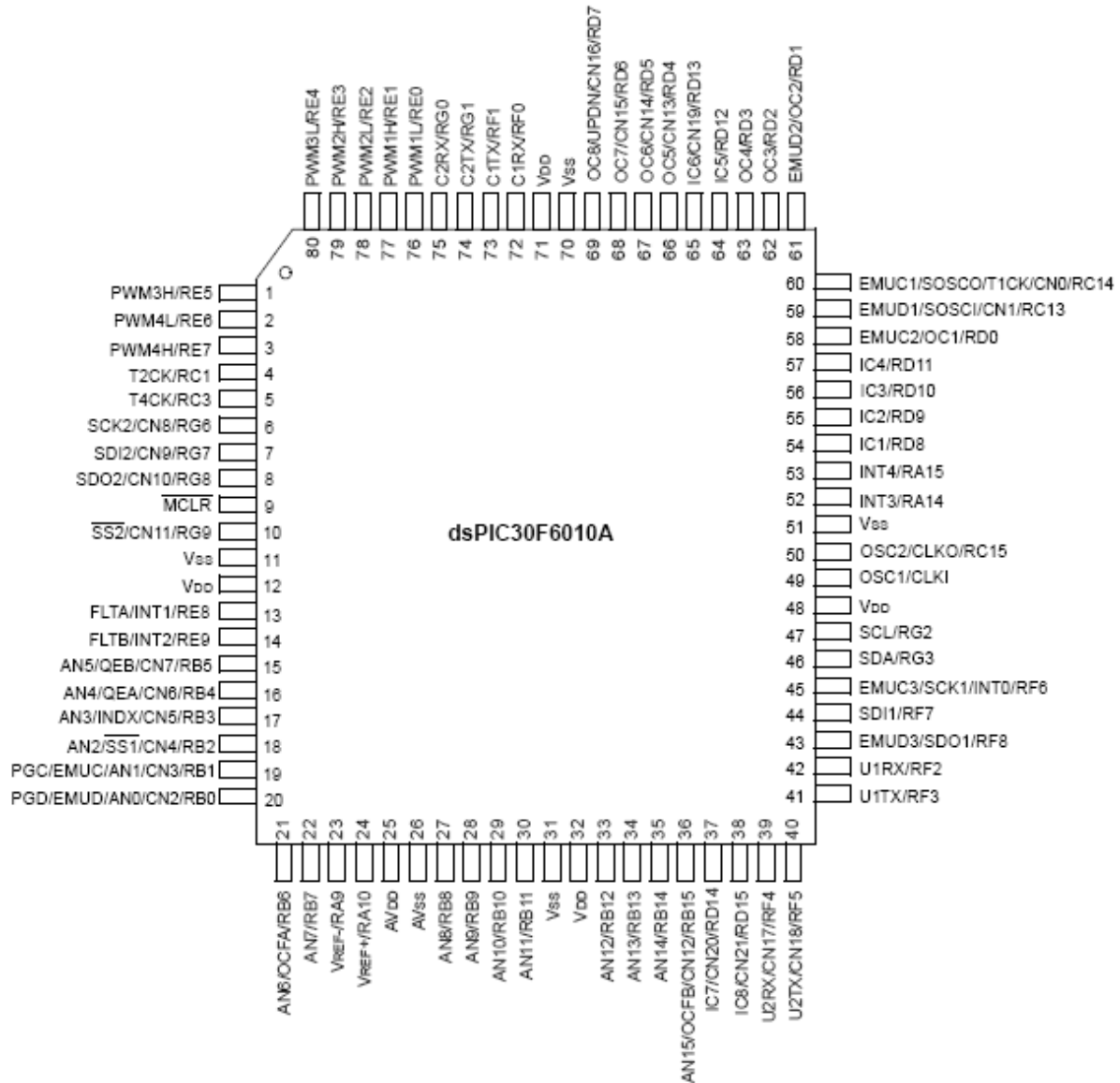
dsPIC30F Motor Control and Power Conversion Family*

Device	Pins	Program Mem. Bytes/Instructions	SRAM Bytes	EEPROM Bytes	Timer 16-bit	Input Cap	Output Comp/Std PWM	Motor Control PWM	A/D 10-bit 1 Msps	Quad Enc	UART	SPI	I ² C™	CAN
dsPIC30F2010	28	12K/4K	512	1024	3	4	2	6 ch	6 ch	Yes	1	1	1	—
dsPIC30F3010	28	24K/8K	1024	1024	5	4	2	6 ch	6 ch	Yes	1	1	1	—
dsPIC30F4012	28	48K/16K	2048	1024	5	4	2	6 ch	6 ch	Yes	1	1	1	1
dsPIC30F3011	40/ 44	24K/8K	1024	1024	5	4	4	6 ch	9 ch	Yes	2	1	1	—
dsPIC30F4011	40/ 44	48K/16K	2048	1024	5	4	4	6 ch	9 ch	Yes	2	1	1	1
dsPIC30F5015	64	66K/22K	2048	1024	5	4	4	8 ch	16 ch	Yes	1	2	1	1
dsPIC30F5016	80	66K/22K	2048	1024	5	4	4	8 ch	16 ch	Yes	1	2	1	1
dsPIC30F6010A	80	144K/48K	8192	4096	5	8	8	8 ch	16 ch	Yes	2	2	1	2
dsPIC30F6015	64	144K/48K	8192	4096	5	8	8	8 ch	16 ch	Yes	2	2	1	1

* This table provides a summary of the dsPIC30F peripheral features. Other available devices in the dsPIC30F Motor Control and Power Conversion Family are shown for feature comparison.

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80-Pin TQFP



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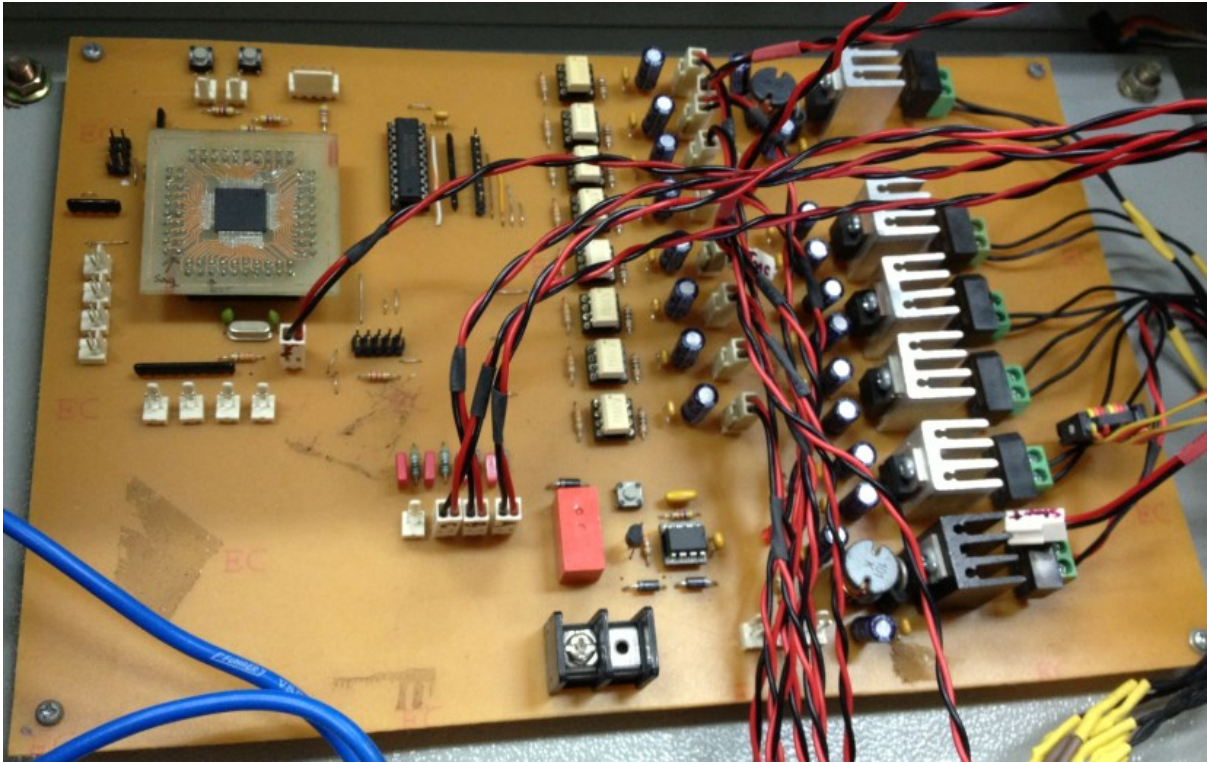


Figure AB-3 A Microcontroller dsPIC30F6010a controller PCB

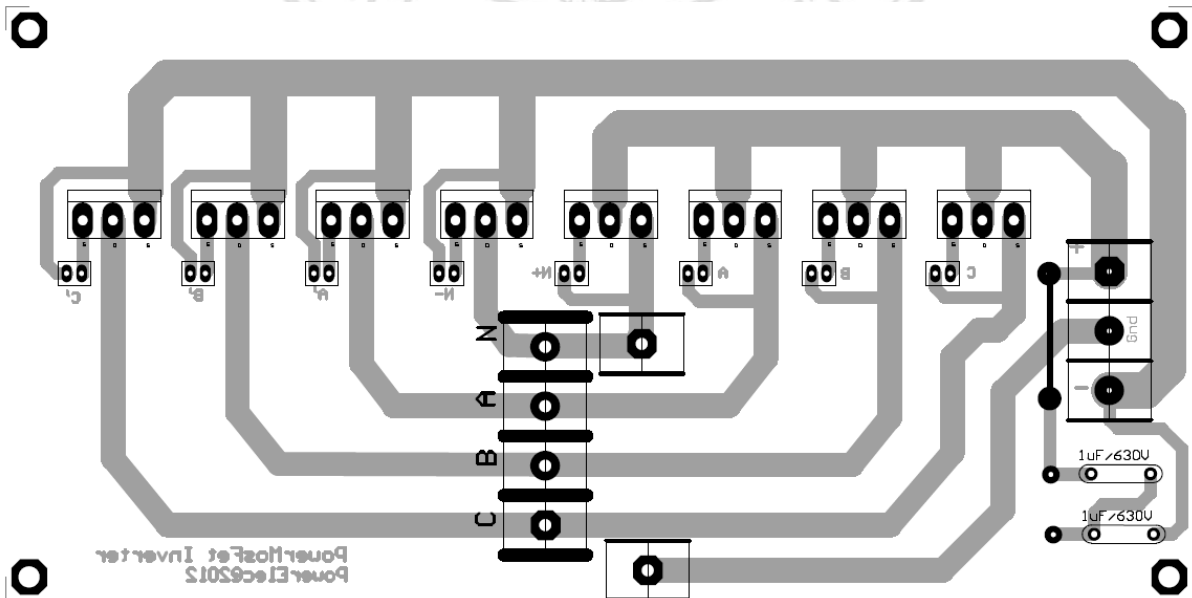


Figure AB-4 IGBT power part PCB

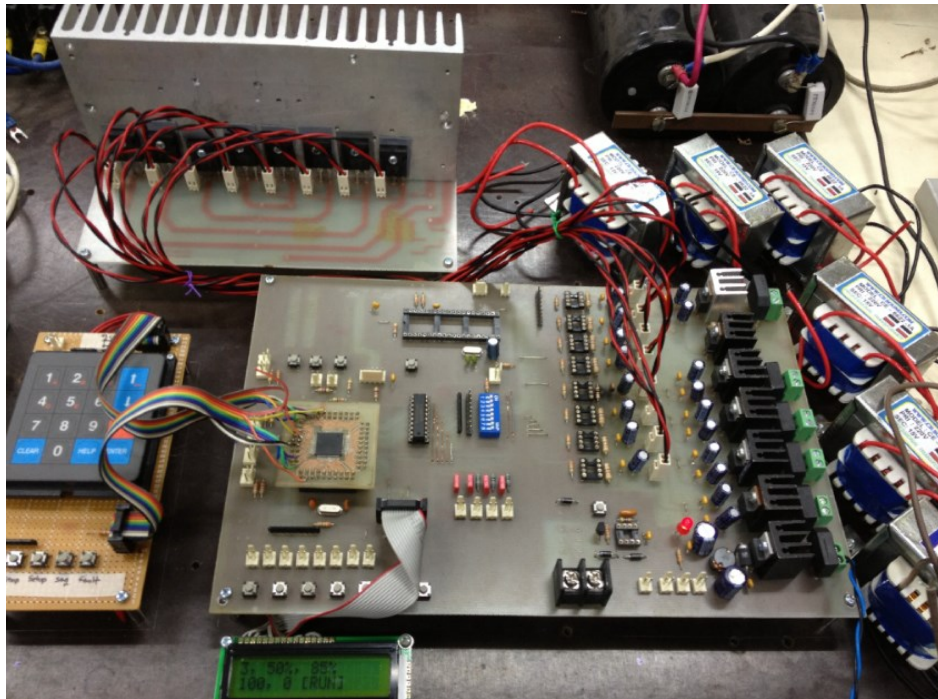


Figure AB-5 Overall system of VSG



Figure ABS-6 Overall system of VSG testing EUT

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Publications Worrajak Muangjai, Suttichai Premrudeepreechacharn¹, and Kosol Oranpiroj, "An Apply Implementation of a Carrier-Based Three-Dimensional Space Vector PWM Technique for Three-Phase Four-Leg Voltage Sag Generator with Microcontroller", Advanced Science Letters, Vol. 19, 2013 Page No. 1249-1254

Worrajak Muangjai¹, Suttichai Premrudeepreechacharn¹, Kohji Higuchi, Kosol Oranpiroj and Wichan Jantee, "An Implementation Algorithm of a Carrier-Based PWM Technique for Three-Phase Four-Leg Voltage Sag Generator with Microcontroller" PEDs2013, Kitakyushu International Conference Center, kitakyoshu, Japan, 22-25 April 2013

W. Muangjai, S. Premrudeepreechacharn, K. Oranpiroj, W. Jantee, "A Three-Phase Four-Leg Voltage Sag Generator with Carrier-Based PWM Technique for Testing Electrical Equipment", Pullman Bangkok King Power, Bangkok, Thailand, 30-31 May 2013

