

## CHAPTER 2

### Preliminaries

The purpose of this chapter is to collect notations, terminologies and elementary results used throughout the thesis.

#### 2.1 Distribution Functions

**Definition 2.1.1.** Let  $X$  be a nonempty set and  $A \subseteq X$ . The *indicator function* of a set  $A$  defined on  $X$  will be denoted by  $\mathbf{1}_A$ , defined by

$$\mathbf{1}_A(x) = \begin{cases} 1 & \text{if } x \in A, \\ 0 & \text{if } x \notin A. \end{cases}$$

**Definition 2.1.2.** Let  $S \subseteq \mathbb{R}$ . A function  $f : S \rightarrow \mathbb{R}$  is said to be *nondecreasing* if

$$f(x) \leq f(y)$$

whenever  $x \leq y$ .

**Definition 2.1.3.** Let  $S \subseteq \mathbb{R}$ . A function  $f : S \rightarrow \mathbb{R}$  is said to be *right-continuous* if for every  $x \in S$  and every  $\epsilon > 0$ , there exists  $\delta > 0$  such that

$$|f(x) - f(y)| < \epsilon$$

whenever  $x \leq y < x + \delta$ .

**Definition 2.1.4.** A function  $F : \mathbb{R} \rightarrow [0, 1]$  is called a (*cumulative*) *distribution function* if  $F$  satisfies the following properties:

- i)  $F$  is right-continuous,
- ii)  $F$  is nondecreasing, and
- iii)  $\lim_{x \rightarrow -\infty} F(x) = 0$  and  $\lim_{x \rightarrow \infty} F(x) = 1$ .

**Example 2.1.1.** A function  $F : \mathbb{R} \rightarrow [0, 1]$  given by

$$F(x) = \begin{cases} 0 & \text{if } x < 0, \\ \frac{x}{1+x} & \text{if } x \geq 0 \end{cases}$$

is a distribution function.

*Proof.* We first show that  $F$  is right-continuous.

Since the function  $x \mapsto 0$  is continuous on  $(-\infty, 0)$  and the function  $x \mapsto \frac{x}{1+x}$  is continuous on  $(0, \infty)$ , we focus only at 0.

Let  $x = 0$  and  $\epsilon > 0$ . Choose  $\delta = \epsilon > 0$ .

For any  $y \in [x, x + \delta) = [0, \delta)$ , we get

$$\begin{aligned} |F(y) - F(x)| &= \left| \frac{y}{1+y} - 0 \right| \\ &= \left| \frac{y}{(1+y)} \right| \\ &\leq y \\ &< \delta \\ &= \epsilon. \end{aligned}$$

Then  $F$  is right-continuous.

Next, we show that  $F$  is nondecreasing.

It is clear that if  $x = y$ , then  $F(x) = F(y)$ . Suppose  $x < y$ .

Case i)  $x < y \leq 0$ .

In this case, we get  $F(x) = F(y) = 0$ .

Case ii)  $x \leq 0 < y$ .

In this case, we get

$$\begin{aligned} F(x) &= 0 \\ &< \frac{y}{1+y} \\ &= F(y). \end{aligned}$$

Case iii)  $0 < x < y$ .

In this case, we get  $x + xy < y + xy$ .

Then  $x(1+y) < y(1+x)$ .

This implies that  $\frac{x}{1+x} < \frac{y}{1+y}$ , that is,  $F(x) < F(y)$ .

Therefore,  $F(x) \leq F(y)$  whenever  $x \leq y$ .

It is obvious that  $\lim_{x \rightarrow -\infty} F(x) = \lim_{x \rightarrow -\infty} 0 = 0$  and  $\lim_{x \rightarrow \infty} F(x) = \lim_{x \rightarrow \infty} \frac{x}{1+x} = 1$ .

Hence,  $F$  is a distribution function. □

**Definition 2.1.5.** Let  $A \subseteq \mathbb{R}$  and  $\Theta \subseteq \mathbb{R}^n$ .

For  $S : A \rightarrow \mathbb{R}$ , define  $\Delta_a^b S = S(b) - S(a)$  for  $a, b \in A$ .

For any  $H : \Theta \times A \rightarrow \mathbb{R}$  the *difference*, denoted by  $\Delta_a^b H$ , is defined by

$$\Delta_a^b H(\theta) = H(\theta, b) - H(\theta, a)$$

for all  $\theta \in \Theta$  and  $a, b \in \mathbb{R}$  in which  $a \leq b$ .

**Definition 2.1.6.** Let  $A \subseteq \mathbb{R}$  and  $H$  be a function from  $A^n$  to  $\mathbb{R}$ .

The *volume* of  $H$ , denoted by  $V_H$ , is defined by

$$V_H \left( \prod_{i=1}^n (a_i, b_i] \right) = \Delta_{a_1}^{b_1} \dots \Delta_{a_n}^{b_n} H$$

where  $a_i, b_i \in A$  such that  $a_i < b_i$  for all  $i = 1, \dots, n$ .

Let  $A \subseteq \mathbb{R}$  and  $H$  be a function from  $A^2$  to  $\mathbb{R}$ .

Given  $a_1, a_2, b_1, b_2 \in A$  in which  $a_1 \leq a_2$  and  $b_1 \leq b_2$ .

Consider

$$\begin{aligned} V_H((a_1, b_1] \times (a_2, b_2]) &= \Delta_{a_1}^{b_1} \Delta_{a_2}^{b_2} H \\ &= \Delta_{a_1}^{b_1} \left( \Delta_{a_2}^{b_2} H \right) \\ &= \Delta_{a_2}^{b_2} H(b_1) - \Delta_{a_2}^{b_2} H(a_1) \\ &= (H(b_1, b_2) - H(b_1, a_2)) - (H(a_1, b_2) - H(a_1, a_2)) \\ &= H(b_1, b_2) - H(b_1, a_2) - H(a_1, b_2) + H(a_1, a_2). \end{aligned}$$

In general, let  $A_i \subseteq \mathbb{R}$  for all  $i = 1, \dots, n$ . For any  $H : \prod_{i=1}^n A_i \rightarrow [0, 1]$  and all  $a_i, b_i \in A_i$  in which  $a_i \leq b_i$ ,

$$V_H \left( \prod_{i=1}^n (a_i, b_i] \right) = \sum_{\vec{v} \in \prod_{i=1}^n \{a_i, b_i\}} (-1)^{N(\vec{v})} H(\vec{v}),$$

where  $N(\vec{v}) = N((v_1, \dots, v_n))$  is the number of  $i$  such that  $v_i = a_i$ .

**Definition 2.1.7.** Let  $A \subseteq \mathbb{R}$ .

A function  $F$  from  $A^n$  to  $\mathbb{R}$  is called *n-increasing function* if the volume of  $F$  is non-negative, that is,

$$V_F \left( \prod_{i=1}^n (a_i, b_i] \right) \geq 0$$

for all  $a_i, b_i \in A$  in which  $a_i \leq b_i$ .

**Definition 2.1.8.** Let  $A_i \subseteq \mathbb{R}$  for all  $i = 1, \dots, n$ . A function  $H : \prod_{i=1}^n A_i \rightarrow [0, 1]$  is said to be *continuous from above* if, for each  $k = 1, \dots, n$  and each  $\epsilon > 0$ , there exists  $\delta > 0$  such that

$$|H(x_1, \dots, x_k, \dots, x_n) - H(x_1, x_2, \dots, y_k, \dots, x_n)| < \epsilon$$

for all  $(x_1, \dots, x_n) \in \prod_{i=1}^n A_i$  and all  $y_k \in A_k \cap [x_k, x_k + \delta)$ .

**Definition 2.1.9.** Let  $F : \mathbb{R}^n \rightarrow [0, 1]$ . Then  $F$  is called an *n-dimensional distribution function* if it satisfies the following properties:

- i)  $\lim_{v_i \rightarrow -\infty, \exists i} F((v_1, \dots, v_n)) = 0$ ,
- ii)  $\lim_{v_i \rightarrow \infty, \forall i} F((v_1, \dots, v_n)) = 1$ ,
- iii)  $F$  is  $n$ -increasing, and
- iv)  $F$  is continuous from above.

Let  $F$  be an  $n$ -dimensional distribution function. For each  $i = 1, \dots, n$ , the function  $F_i : \mathbb{R} \rightarrow [0, 1]$  defined by  $F_i(x_i) = \lim_{v_j \rightarrow \infty, \forall j \neq i} F((v_1, \dots, v_n))$  is called the *(i-th) marginal distribution function* of  $F$ .

**Remark 2.1.2.** Every marginal distribution function of an  $n$ -dimensional distribution function is a distribution function.

Next, we will give an example of a 2-dimensional distribution function and its marginals.

**Example 2.1.3.** A function  $F : \mathbb{R}^2 \rightarrow [0, 1]$  given by

$$F(x, y) = \begin{cases} 1 & \text{if } x \geq 0, y \geq 0, \\ 0 & \text{otherwise} \end{cases}$$

is a 2-dimensional distribution function.

*Proof.* It is easy to see that

$$\lim_{x \rightarrow -\infty} F(x, y) = 0,$$

$$\lim_{y \rightarrow -\infty} F(x, y) = 0,$$

$$\lim_{x \rightarrow \infty} \lim_{y \rightarrow \infty} F(x, y) = 1 \quad \text{and}$$

$$\lim_{y \rightarrow \infty} \lim_{x \rightarrow \infty} F(x, y) = 1.$$

We next show that  $F$  is a 2-increasing function.

Since  $V_F((a, b] \times (c, d]) = F(b, d) + F(a, c) - F(b, c) - F(a, d)$  and range of the function  $F$  is  $\{0, 1\}$ , we have three cases to consider, when  $F(b, c) = 1, F(a, d) = 1$  and  $F(b, c) = 0 = F(a, d)$ .

If  $F(b, c) = 0 = F(a, d)$ , then the volume of  $F$  is not less than 0, that is, we have only two cases to consider, when  $F(b, c) = 1$  or  $F(a, d) = 1$ .

Case i)  $F(b, c) = 1$ . By the definition of  $F$ , we obtain that  $b, c \geq 0$ .

Since  $c \leq d$ , we have  $b, c, d \geq 0$ .

If  $a < 0$ , then

$$\begin{aligned} V_F((a, b] \times (c, d]) &= F(b, d) + F(a, c) - F(b, c) - F(a, d) \\ &= 1 + 0 - 1 - 0 \\ &= 0. \end{aligned}$$

If  $a \geq 0$ , then

$$\begin{aligned} V_F((a, b] \times (c, d]) &= F(b, d) + F(a, c) - F(b, c) - F(a, d) \\ &= 1 + 1 - 1 - 1 \\ &= 0. \end{aligned}$$

Case ii)  $F(a, d) = 1$ . By the definition of  $F$ , we obtain that  $a, d \geq 0$ .

Since  $a \leq b$ , we have  $a, b, d \geq 0$ .

If  $c < 0$ , then

$$\begin{aligned} V_F((a, b] \times (c, d]) &= F(b, d) + F(a, c) - F(b, c) - F(a, d) \\ &= 1 + 0 - 0 - 1 \\ &= 0. \end{aligned}$$

If  $c \geq 0$ , then

$$\begin{aligned} V_F((a, b] \times (c, d]) &= F(b, d) + F(a, c) - F(b, c) - F(a, d) \\ &= 1 + 1 - 1 - 1 \\ &= 0. \end{aligned}$$

Therefore,  $V_F((a, b] \times (c, d]) \geq 0$ .

Finally, we show that  $F$  is continuous from above.

Let  $x, y \in \mathbb{R}$  and  $\epsilon > 0$ . Then we have four cases to consider.

Case i)  $x \geq 0, y \geq 0$ .

Choose  $\delta = \epsilon > 0$ .

For any  $x^+ \in [x, x + \delta)$ ,  $|F(x, y) - F(x^+, y)| = |1 - 1| = 0 < \epsilon$ .

Similarly,  $|F(x, y^+) - F(x, y)| < \epsilon$  for all  $y^+ \in [y, y + \delta)$ .

Case ii)  $x < 0, y \geq 0$ .

Choose  $\delta_1 = -\frac{x}{2} > 0$  and  $\delta_2 = \epsilon > 0$ .

For any  $x^+ \in [x, x + \delta_1)$ ,  $|F(x, y) - F(x^+, y)| = |0 - 0| = 0 < \epsilon$

and for any  $y^+ \in [y, y + \delta_2)$ ,  $|F(x, y^+) - F(x, y)| = |0 - 0| = 0 < \epsilon$ .

Case iii)  $x \geq 0, y < 0$ .

Choose  $\delta_1 = \epsilon > 0$  and  $\delta_2 = -\frac{y}{2} > 0$ .

For any  $x^+ \in [x, x + \delta_1)$ ,  $|F(x, y) - F(x^+, y)| = |0 - 0| = 0 < \epsilon$

and for any  $y^+ \in [y, y + \delta_2)$ ,  $|F(x, y^+) - F(x, y)| = |0 - 0| = 0 < \epsilon$ .

Case iv)  $x < 0, y < 0$ .

Choose  $\delta_1 = -\frac{x}{2} > 0$  and  $\delta_2 = -\frac{y}{2} > 0$ .

For any  $x^+ \in [x, x + \delta_1)$ ,  $|F(x, y) - F(x^+, y)| = |0 - 0| = 0 < \epsilon$

and for any  $y^+ \in [y, y + \delta_2)$ ,  $|F(x, y^+) - F(x, y)| = |0 - 0| = 0 < \epsilon$ .

Hence,  $F$  is a continuous from above function.

Therefore,  $F$  is a 2-dimensional distribution function.

If  $F_1 : \mathbb{R} \rightarrow [0, 1]$  is defined by

$$F_1(x) = \begin{cases} 1 & \text{if } x \geq 0, \\ 0 & \text{if } x < 0 \end{cases}$$

and  $F_2 : \mathbb{R} \rightarrow [0, 1]$  is defined by

$$F_2(y) = \begin{cases} 1 & \text{if } y \geq 0, \\ 0 & \text{if } y < 0, \end{cases}$$

then  $F_1$  and  $F_2$  are marginal distribution functions of  $F$ . □

## 2.2 Probability Measures

**Definition 2.2.1.** Let  $\Omega$  be a nonempty set and  $2^\Omega$  denote the power set of  $\Omega$ . A class  $\Sigma \subseteq 2^\Omega$  is called a  $\sigma$ -algebra on  $\Omega$  if it satisfies the following properties:

i)  $\emptyset \in \Sigma$ ,

- ii) if  $E \in \Sigma$ , then  $E^C = \Omega \setminus E \in \Sigma$ , and
- iii) if  $E_1, E_2, E_3, \dots \in \Sigma$ , then  $\bigcup_{k=1}^{\infty} E_k \in \Sigma$ .

The ordered pair  $(\Omega, \Sigma)$  is called a *measurable space* and the elements of  $\Sigma$  are called *measurable sets*.

Let  $\Omega$  be a nonempty set. For any  $\Lambda \subseteq 2^\Omega$ , denote the intersection of all  $\sigma$ -algebras containing  $\Lambda$  by  $\sigma(\Lambda)$ . Note that  $\sigma(\Lambda)$  is the smallest  $\sigma$ -algebra containing  $\Lambda$ .

**Definition 2.2.2.** Let  $(X, \Sigma_X)$  and  $(Y, \Sigma_Y)$  be two measurable spaces.

A function  $f : X \rightarrow Y$  is said to be *measurable function* if  $f^{-1}(E) \in \Sigma_X$  for all  $E \in \Sigma_Y$ .

**Definition 2.2.3.** Let  $\Omega \subseteq \mathbb{R}^n$  where  $n \in \mathbb{N}$  and  $\mathcal{O}$  be the set of all open subsets of  $\Omega$ . Then  $\sigma(\mathcal{O})$  is called the *Borel  $\sigma$ -algebra on  $\Omega$*  which specifically is denoted by  $\mathcal{B}(\Omega)$ . The elements of  $\mathcal{B}(\Omega)$  are called *Borel sets*.

**Definition 2.2.4.** Let  $\Omega$  be a nonempty set,  $\Sigma$  be a  $\sigma$ -algebra on  $\Omega$  and  $\mathcal{J} \subseteq \mathbb{N}$ . A function  $\mu : \Sigma \rightarrow [0, 1]$  is called a *probability measure* if it satisfies the following properties:

- i)  $\mu(\Omega) = 1$ , and
- ii) for any countable collection  $\{E_i\}_{i \in \mathcal{J}}$  of elements in  $\Sigma$  such that  $E_j \cap E_k = \emptyset$  when  $j, k \in \mathcal{J}$  and  $j \neq k$ ,  $\mu\left(\bigcup_{i \in \mathcal{J}} E_i\right) = \sum_{i \in \mathcal{J}} \mu(E_i)$ .

A *probability space* is a triplet  $(\Omega, \Sigma, \mu)$ .

**Definition 2.2.5.** Let  $\mathcal{B}([0, 1])$  be the Borel  $\sigma$ -algebra on  $[0, 1]$ ,

$$\Gamma = \{(a, b] \subseteq [0, 1] \mid 0 \leq a < b \leq 1\} \cup \{\emptyset\},$$

and  $\tau : \Gamma \rightarrow [0, 1]$  be defined by  $\tau(A) = \begin{cases} b - a & \text{if } A = (a, b], \\ 0 & \text{if } A = \emptyset. \end{cases}$

A function  $\lambda : \mathcal{B}([0, 1]) \rightarrow [0, 1]$  defined by

$$\lambda(A) = \inf \left\{ \sum_{n=1}^{\infty} \tau(D_n) \mid A \subseteq \bigcup_{n=1}^{\infty} D_n, (D_n)_{n=1}^{\infty} \subset \Gamma \right\}$$

is called the *Lebesgue measure on  $[0, 1]$* .

**Remark 2.2.1.**  $\lambda$  is a probability measure on  $[0, 1]$ .

**Theorem 2.2.2.** Let  $\Omega$  be a nonempty set and  $\Lambda \subseteq 2^\Omega$  be nonempty and closed under finite intersections. If  $P_1$  and  $P_2$  are probability measures on  $\sigma(\Lambda)$  such that  $P_1 = P_2$  on  $\Lambda$ , then  $P_1 = P_2$  on  $\sigma(\Lambda)$ .

**Definition 2.2.6.** Let  $(\Omega, \mathcal{A}, \mathbb{P})$  be a probability space. A *random variable* is a Borel measurable function from  $\Omega$  to  $\mathbb{R}$ . A *random vector* is a Borel measurable function from  $\Omega$  to  $\mathbb{R}^n$ .

**Definition 2.2.7.** For any random variable  $X$  defined on a probability space  $(\Omega, \mathcal{A}, \mathbb{P})$ , its *distribution function* is a function  $F_X$  defined by

$$F_X(x) = \mathbb{P}(X \leq x)$$

for all  $x \in \mathbb{R}$ .

**Definition 2.2.8.** For any random vector  $(X_1, \dots, X_n)$  defined on a probability space  $(\Omega, \mathcal{A}, \mathbb{P})$ , its *(joint) distribution function* is a function  $H$  defined by

$$H(x_1, \dots, x_n) = \mathbb{P}(X_1 \leq x_1, \dots, X_n \leq x_n)$$

for all  $x_i \in \mathbb{R}$  where  $i = 1, \dots, n$ .

Here and henceforth, we define  $(x_1, \dots, x_n) < (y_1, \dots, y_n)$  if  $x_i < y_i$  for all  $i = 1, \dots, n$  and  $(x_1, \dots, x_n) \leq (y_1, \dots, y_n)$  if  $x_i \leq y_i$  for all  $i = 1, \dots, n$ .

Denote also  $(\vec{a}, \vec{b}] = (a_1, b_1] \times \dots \times (a_n, b_n]$  where  $\vec{a} = (a_1, \dots, a_n)$  and  $\vec{b} = (b_1, \dots, b_n)$ .

**Definition 2.2.9.** Let  $X$  be a random vector with the  $F_X$ .

A random vector  $X$  is said to be *(absolutely) continuous* if there is a function  $f_X$  such that  $F_X(x) = \int_{(-\infty, x]} f_X d\lambda$  for all  $x \in \mathbb{R}$ . A function  $f_X$  is called the density function of  $F_X$ .

**Definition 2.2.10.** An  $n$ -dimensional random vector  $U$  is said to be *uniform* if its distribution function  $F_U$  is the product function  $\Pi$ , that is,

$$F_U(\vec{u}) = \Pi(\vec{u}) = \prod_{i=1}^n u_i$$

for all  $\vec{u} = (u_1, \dots, u_n) \in [0, 1]^n$ .

**Proposition 2.2.3.** Let  $X$  and  $Y$  be random vectors with distribution functions  $F_X$  and  $F_Y$ , respectively. Then the three following properties are equivalent:

- i)  $X$  and  $Y$  are independent,
- ii)  $\mathbb{P}(X \in A, Y \in B) = \mathbb{P}(X \in A)\mathbb{P}(Y \in B)$  for all measurable sets  $A$  and  $B$ , and
- iii)  $F_{X,Y}(\vec{x}, \vec{y}) = F_X(\vec{x})F_Y(\vec{y})$  for all  $\vec{x}, \vec{y} \in \mathbb{R}^n$ .



**Definition 2.2.11.** A random vector  $Y$  is said to be *completely dependent* on a random vector  $X$  if  $Y$  takes only one value for each value of  $X$  with probability one, that is, there is a measurable function  $f$  such that  $Y = f(X)$  almost everywhere.

**Definition 2.2.12.** Let  $X$  and  $Y$  be random vectors.

The *conditional distribution function*  $F_{Y|X}$  of  $Y$  given  $X$  is defined by

$$\begin{aligned} F_{Y|X}(y|x) &= \lim_{h \searrow 0} \frac{\mathbb{P}(x-h < X \leq x+h, Y \leq y)}{\mathbb{P}(x-h < X \leq x+h)} \\ &= \lim_{h \searrow 0} \frac{V_{F_{X,Y}}((x-h, x+h] \times (-\infty, y])}{V_{F_X}((x-h, x+h])}. \end{aligned}$$

**Lemma 2.2.4.** Let  $X$  and  $Y$  be random vectors. Given the distribution function  $F_Y$  of  $Y$  and the conditional distribution function  $F_{Y|X}$  of  $Y$  given  $X$ . Then

$$\int F_{Y|X}(y|x) dF_X(x) = F_Y(y).$$

*Proof.* Denote  $\mu_y(A) = \mathbb{P}(Y \leq y | X \in A)$  and  $\mu(A) = \mathbb{P}(X \in A)$ .

Then  $\mu_y$  is absolutely continuous with respect to  $\mu$ .

By Lebesgue point theorem,  $\lim_{h \searrow 0} \frac{1}{\mu(\mathcal{B}(x, \epsilon))} \int_{\mathcal{B}(x, \epsilon)} \frac{d\mu_y}{d\mu} d\mu = \frac{\mu_y(\mathcal{B}(x, \epsilon))}{\mu(\mathcal{B}(x, \epsilon))}$  converges to  $\frac{d\mu_y}{d\mu}(x)$ .

Thus,  $F_{Y|X}(y|x) = \frac{d\mu_y}{d\mu}(x)$ . Therefore,

$$\begin{aligned} \int F_{Y|X}(y|x) dF_X(x) &= \int \frac{d\mu_y}{d\mu}(x) d\mu(x) \\ &= \mu(\mathbb{R}^n) \\ &= F_Y(y). \end{aligned}$$

□

**Lemma 2.2.5.** Let  $X$  and  $Y$  be random vectors. Given the distribution function  $F_Y$  of  $Y$  and the conditional distribution function  $F_{Y|X}$  of  $Y$  given  $X$ . Then  $X$  and  $Y$  are independent if and only if  $F_{Y|X} = F_Y$  a.e. with respect to the product of the distribution of  $X$  and  $Y$ .

*Proof.* Let  $X$  and  $Y$  be independent random vectors, we have

$$\begin{aligned} F_{Y|X}(y|x) &= \lim_{h \searrow 0} \frac{V_{F_{X,Y}}((x-h, x+h] \times (-\infty, y])}{V_{F_X}((x-h, x+h])} \\ &= \lim_{h \searrow 0} \frac{V_{F_X}(x-h, x+h] V_{F_Y}(-\infty, y]}{V_{F_X}((x-h, x+h])} \\ &= \lim_{h \searrow 0} V_{F_Y}(-\infty, y] \\ &= F_Y(y). \end{aligned}$$

Conversely, we show that  $X$  and  $Y$  are independent when  $F_{Y|X} = F_Y$ .

Let  $F_{Y|X} = F_Y$  and  $t \in \mathbb{R}$ . Consider

$$\begin{aligned}
 F_{X,Y}(x, t) &= \mathbb{P}(X \leq x, Y \leq t) \\
 &= \int_{(-\infty, t]} \mathbb{P}(Y \leq y | X = x) dF_X(x) \\
 &= \int_{(-\infty, t]} F_{Y|X}(y|x) dF_X(x) \\
 &= \int_{(-\infty, t]} F_Y(y) dF_X(x) \\
 &= F_X(x) F_Y(t) \quad \text{a.e.}
 \end{aligned}$$

By Proposition 2.2.3, we obtain that  $X$  and  $Y$  are independent. □

## 2.3 Copulas

**Definition 2.3.1.** An  $n$ -dimensional copula or  $n$ -copula is a continuous function  $C : [0, 1]^n \rightarrow [0, 1]$  satisfying the following properties:

- i)  $C$  is an  $n$ -increasing,
- ii)  $C$  is grounded, that is,  $C(u_1, \dots, u_n) = 0$  whenever  $u_i = 0$  for some  $i = 1, \dots, n$ , and
- iii)  $C$  has uniform marginals, that is,  $C(u_1, \dots, u_n) = u_i$  whenever  $u_j = 1$  for all  $j \neq i$ .

**Example 2.3.1.** Let  $\vec{u} = (u_1, \dots, u_n) \in [0, 1]^n$ . The function  $\Pi^n : [0, 1]^n \rightarrow [0, 1]$  defined by  $\Pi^n(u_1, \dots, u_n) = u_1 \cdots u_n$  is an  $n$ -copula.

*Proof.* Let  $\vec{u} = (u_1, \dots, u_n) \in [0, 1]^n$ .

- i) If  $\vec{u}$  has at least one coordinate which is equal to 0, then  $\Pi^n(\vec{u}) = 0$ .
- ii) If all coordinates of  $\vec{u}$  are equal to 1 except possibly  $u_k$ , then  $\Pi^n(\vec{u}) = u_k$ .
- iii) Next, we show that  $\Pi^n$  is  $n$ -increasing.  
Let  $\left[ \vec{a}, \vec{b} \right] = (a_1, b_1] \times \cdots \times (a_n, b_n]$ .

Since  $b_i - a_i \geq 0$  for all  $i = 1, \dots, n$  and

$$\begin{aligned}
(b_1 - a_1)(b_2 - a_2) \cdots (b_n - a_n) &= \sum_{\forall i=1, \dots, n; v_i \in \{b_i, -a_i\}} v_1 \cdots v_n \\
&= \sum_{\forall i=1, \dots, n; v_i \in \{b_i, -a_i\}} \Pi^n(v_1, \dots, v_n) \\
&= \sum_{\vec{v} \in \prod_{i=1}^n \{b_i, -a_i\}} \Pi^n(\vec{v}) \\
&= \sum_{\vec{v} \in \prod_{i=1}^n \{b_i, a_i\}} (-1)^{N(\vec{v})} \Pi^n(\vec{v}) \\
&= V_{\Pi^n} \left( \left( \vec{a}, \vec{b} \right) \right),
\end{aligned}$$

it follows that  $V_{\Pi^n} \left( \left( \vec{a}, \vec{b} \right) \right) = (b_1 - a_1)(b_2 - a_2) \cdots (b_n - a_n) \geq 0$ .

Hence,  $\Pi^n$  is  $n$ -increasing.

By i)–iii), we obtain that  $\Pi^n$  is an  $n$ -copula. □

**Theorem 2.3.2.** [6] *Let  $H$  be an  $n$ -dimensional distribution function of a random vector  $(X_1, \dots, X_n)$  with marginals  $F_1, \dots, F_n$ . Then there exists an  $n$ -copula  $C$  such that*

$$H(x_1, \dots, x_n) = C(F_1(x_1), \dots, F_n(x_n)) \quad (2.1)$$

for all  $x_1, \dots, x_n \in \mathbb{R}$ .

Any copula  $C$  satisfying equation (2.1) is said to be associated with  $(X_1, \dots, X_n)$ .

If  $F_1, \dots, F_n$  are all continuous, then  $C$  is unique; otherwise,  $C$  is uniquely determined on  $\text{Ran}(F_1) \times \dots \times \text{Ran}(F_n)$  where  $\text{Ran}(F)$  is the range of  $F$ .

Conversely, if  $C$  is an  $n$ -copula and  $F_1, \dots, F_n$  are distribution functions, then the function  $H$  defined by (2.1) is an  $n$ -dimensional distribution.

A joint distribution function of uniform random vectors is called a *linkage*.

Note that a linkage is always a copula.

For each distribution function  $F_X$  of an absolutely continuous random vector  $X = (X_1, \dots, X_n)$ , define a *transformation*  $\Psi_{F_X} : \mathbb{R}^n \rightarrow [0, 1]^n$  by letting

$$\Psi_{F_X}(x_1, \dots, x_n) = (F_{X_1}(x_1), F_{X_2|X_1}(x_2|x_1), \dots, F_{X_n|(X_1, \dots, X_{n-1})}(x_n|(x_1, \dots, x_{n-1})))$$

for all  $(x_1, \dots, x_n) \in \mathbb{R}^n$ . It is known that  $U = \Psi_{F_X}(X)$  has uniform distribution (see in [5]). H. Li, M. Scarsini, and M. Shaked [5] showed that for each random variables  $X_1, \dots, X_n$  with an absolutely continuous joint distribution  $F$ , these random variables  $U_1, \dots, U_n$  are independent uniform  $[0, 1]$  whenever  $(U_1, \dots, U_n) = \Psi_F(X_1, \dots, X_n)$ . Similarly,

if the univariate random variable  $X$  has the continuous distribution function  $F$ , then  $F(X)$  is a uniform  $[0, 1]$  random variable.

By inverting,  $\Psi_F$  can express the  $X$ 's as functions of the independent uniform random variables  $U_1, \dots, U_n$ . Denote

$$x_1 = F^{-1}(u_1) \quad (2.2)$$

and, by induction,

$$x_i = F_{i|1, \dots, i-1}^{-1}(u_i | x_1, \dots, x_{i-1}), \quad i = 2, \dots, n. \quad (2.3)$$

Consider the transformation  $\Psi^* : [0, 1]^n \rightarrow \mathbb{R}^n$  defined by (here the  $x_i$ 's are functions of the  $u_i$ 's as given in (2.2) and (2.3))

$$\Psi_F^*(u_1, \dots, u_n) = (x_1, \dots, x_n), \quad (u_1, \dots, u_n) \in [0, 1]^n.$$

Let

$$(\hat{X}_1, \dots, \hat{X}_n) = \Psi_F^*(U_1, \dots, U_n).$$

Then  $(\hat{X}_1, \dots, \hat{X}_n)$  has the same distribution as  $(X_1, \dots, X_n)$ .

In fact, it is well known, if  $F$  is absolutely continuous, then

$$\Psi_F^* \Psi_F(X_1, X_2, \dots, X_n) =_{\text{a.s.}} (X_1, X_2, \dots, X_n),$$

where  $=_{\text{a.s.}}$  denotes an equality almost surely under the probability measure associated with  $F$ .

Since  $U_i = \Psi_i(X_i)$  is uniform, the joint distribution of  $U_1, \dots, U_k$  is a linkage.

We called this linkage, the *linkage associated with  $X_1, \dots, X_k$*  and will be denoted by  $C_{X_1, \dots, X_k}$ .

We will also denote  $C_{X_k | X_1, \dots, X_{k-1}}$  the conditional distribution function of  $U_k$  given  $(U_1, \dots, U_{k-1})$ .

For further information on linkages, see [5].

**Example 2.3.3.** Let  $X$  and  $Y$  be random vectors with dimensions  $m$  and  $n$ , respectively, with FGM-copula

$$C_\theta(\vec{u}, \vec{v}) = \Pi(\vec{u})\Pi(\vec{v}) + \theta\Pi(\vec{u})\Pi(\vec{v})\Pi(\vec{1} - \vec{u})\Pi(\vec{1} - \vec{v})$$

where  $\theta \in [-1, 1]$  as their joint distribution.

Then the marginals  $F_X$  and  $F_Y$  of  $C_\theta$  are defined by  $F_X(\vec{u}) = \Pi(\vec{u})$  and  $F_Y(\vec{v}) = \Pi(\vec{v})$ .

Therefore,  $X$  and  $Y$  are uniform random vectors, that is,  $C_\theta$  is the linkage.

## Measure of Complete Dependence

Let  $X$  and  $Y$  be two random variables. The random variable  $Y$  is *completely dependent* on  $X$  if there is a Borel measurable function  $f$  such that  $\mathbb{P}(Y = f(X)) = 1$ . If  $Y$  is completely dependent on  $X$ , and  $X$  is completely dependent on  $Y$ , then  $X$  and  $Y$  are called *mutually completely dependent* (m.c.d.).

In 2010, Siburg and Stoimenov [1] defined a measure of dependence

$$\begin{aligned}\omega(X, Y) &= \sqrt{3 \int_{[0,1]^2} \left[ \left( \frac{\partial}{\partial x} C_{X,Y}(x, y) - y \right)^2 + \left( \frac{\partial}{\partial y} C_{X,Y}(x, y) - x \right)^2 \right] dx dy} \\ &= \sqrt{3 \int_{[0,1]^2} \left[ \left( \frac{\partial}{\partial x} C_{X,Y}(x, y) \right)^2 + \left( \frac{\partial}{\partial y} C_{X,Y}(x, y) \right)^2 \right] dx dy} - 2\end{aligned}$$

for any continuous random variables  $X$  and  $Y$ . In their works, it was shown that, for any random variables  $X$  and  $Y$  with continuous distribution functions,  $\omega(X, Y)$  has the following properties:

- i)  $\omega(X, Y) = \omega(Y, X)$ ,
- ii)  $0 \leq \omega(X, Y) \leq 1$ ,
- iii)  $\omega(X, Y) = 0$  if and only if  $X$  and  $Y$  are independent,
- iv)  $\omega(X, Y) = 1$  if and only if  $X$  and  $Y$  are m.c.d.,
- v)  $\omega(X, Y) \in (\sqrt{2}/2, 1]$  if  $Y$  is completely dependent on  $X$  (or vice versa),
- vi) If  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  are strictly monotone functions, then  $\omega(f(X), g(Y)) = \omega(X, Y)$ , and
- vii) If  $(X_n, Y_n)_{n \in \mathbb{N}}$  is a sequence of pairs of random variables with continuous marginal distribution functions and copulas  $(C_n)_{n \in \mathbb{N}}$  and if  $\lim_{n \rightarrow \infty} \|C_n - C\| = 0$ , then  $\lim_{n \rightarrow \infty} \omega(X_n, Y_n) = \omega(X, Y)$  where  $\|\cdot\|$  is a modified Sobolev norm and  $C$  is a copula associated with random variables  $X$  and  $Y$ .

Let  $\mathfrak{F}$  be the set of all bivariate distribution functions with continuous marginal distribution functions, as well as  $\mathfrak{X}$  be the set of all bivariate random vectors with distribution functions in  $\mathfrak{F}$ . Dette et al. [2] defined a measure  $r : \mathfrak{X} \rightarrow [0, 1]$  via the following formula

$$r(X, Y) = 6 \int_0^1 \int_0^1 F_{V|U}(v|u)^2 dv du - 2.$$

Since  $F_{V|U}(v|u) = \frac{\partial}{\partial u} C_{X,Y}(u, v)$ , we obtain that

$$r(X, Y) = 6 \left\| \frac{\partial}{\partial u} C_{X,Y} \right\|_2^2 - 2$$

where  $\|\cdot\|$  denotes the  $L^2$ -norm.

In their works, it was shown that, if  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  are strictly monotone functions, then  $r(f(X), g(Y)) = r(X, Y)$ .

Moreover,  $r$  can be viewed as a functional on the set of copulas  $\mathfrak{C}$ , and we write  $r(C_{X,Y}) = r(X, Y)$  which can be considered as an asymmetric version of  $\omega(X, Y)$ , that is,  $\omega(X, Y) = \sqrt{\frac{r(X, Y) + r(Y, X)}{2}}$ .

Let  $\mathcal{C}$  be the set of all two-dimensional copulas and  $\mathcal{C}_d$  be the class of all completely dependent copulas. During the same period, Trutschnig [3] also defined a measure of complete dependence  $\zeta_1$  based on the Markov kernel associated with  $X$  and  $Y$ .

When written using the copula  $C_{X,Y}$  associated with  $X$  and  $Y$ ,

$$\zeta_1(Y|X) = 3 \int \int \left| \frac{\partial}{\partial x} C_{X,Y}(x, y) - y \right| dx dy$$

and showed that for every  $C \in \mathcal{C}$ ,  $\zeta_1(C) \in [0, 1]$ . Furthermore,  $\zeta_1(C) = 1$  if and only if  $C \in \mathcal{C}_d$ , that is, all completely dependent copulas have a maximum dependence measure.

Both  $r$  and  $\zeta_1$  are similar in the sense that both measures reach the maximum value if and only if the random variable  $Y$  is a measurable function of the random variable  $X$ .

Recently, Tasena and Dhompongsa [4] also defined measures of complete dependence

$$\omega_k(Y|X) = \left[ \int \int \left| F_{Y|X}(y|x) - \frac{1}{2} \right|^k dF_X(x) dF_Y(y) \right]^{\frac{1}{k}}$$

and

$$\bar{\omega}_k(Y|X) = \left[ \frac{\omega_k^k(Y|X) - \hat{\omega}_k(Y)}{\omega_k^k(Y|Y) - \hat{\omega}_k(Y)} \right]^{\frac{1}{k}}$$

where  $\hat{\omega}_k(Y) = \int \left| F_Y(y) - \frac{1}{2} \right|^k dF_Y(y)$  for any random vectors  $X$  and  $Y$ .

In their works, it was shown that  $\omega_k$  has the following properties:

- i)  $\omega_k(Y^\perp|X^\perp) \leq \omega_k(Y|X) \leq \omega_k(Y|Y)$  where  $(Y^\perp, X^\perp)$  have the same marginals as  $(Y, X)$  but  $X^\perp$  and  $Y^\perp$  are independent,
- ii)  $\omega_k(Y^\perp|X^\perp) = 0$  and  $\omega_k(Y|Y) = 1$ ,
- iii)  $\omega_k(Y^\perp|X^\perp) = \omega_k(Y|X)$  if and only if  $X$  and  $Y$  are independent,
- iv)  $\omega_k(Y|X) = \omega_k(Y|Y)$  if and only if  $Y$  is a function of  $X$ ,

- v)  $\omega_k(Y, Y, Z|X) = \omega_k(Y, Z|X)$  for all random vectors  $X, Y$ , and  $Z$ ,
- vi)  $\omega_k(Y|X, X, Z) = \omega_k(Y|X, Z)$  for all random vectors  $X, Y$ , and  $Z$ ,
- vii)  $\omega_k(Y|X, Z) \geq \omega_k(Y|X)$  for all random vectors  $X, Y$ , and  $Z$ ,
- viii)  $\omega_k(Y, f(X)|X) \geq (Y|X)$  for all measurable functions  $f$  and random vectors  $X$  and  $Y$ ,
- ix)  $\omega_k(Y|f(X)) \leq \omega_k(Y|X)$  for all measurable functions  $f$  and random vectors  $X$  and  $Y$ ,

while  $\bar{\omega}_k(Y|X)$  satisfies the properties:

- i)  $\bar{\omega}_k(Y^\perp|X^\perp) \leq \bar{\omega}_k(Y|X) \leq \bar{\omega}_k(Y|Y)$  where  $(Y^\perp, X^\perp)$  have the same marginals as  $(Y, X)$  but  $X^\perp$  and  $Y^\perp$  are independent,
- ii)  $\bar{\omega}_k(Y^\perp|X^\perp) = 0$  and  $\bar{\omega}_k(Y|Y) = 1$ ,
- iii)  $\bar{\omega}_k(Y^\perp|X^\perp) = \bar{\omega}_k(Y|X)$  if and only if  $X$  and  $Y$  are independent,
- iv)  $\bar{\omega}_k(Y|X) = \bar{\omega}_k(Y|Y)$  if and only if  $Y$  is a function of  $X$ ,
- v)  $\bar{\omega}_k(Y, Y, Z|X) = \bar{\omega}_k(Y, Z|X)$  for all random vectors  $X, Y$ , and  $Z$ ,
- vi)  $\bar{\omega}_k(Y|X, X, Z) = \bar{\omega}_k(Y|X, Z)$  for all random vectors  $X, Y$ , and  $Z$ ,
- vii)  $\bar{\omega}_k(Y|X, Z) \geq \bar{\omega}_k(Y|X)$  for all random vectors  $X, Y$ , and  $Z$ , and
- viii)  $\bar{\omega}_k(Y|f(X)) \leq \bar{\omega}_k(Y|X)$  for all measurable functions  $f$  and random vectors  $X$  and  $Y$ . Moreover, if  $f$  is invertible, then  $\bar{\omega}_k(Y|f(X)) = \bar{\omega}_k(Y|X)$ .

Moreover,

$$\bar{\omega}_2(Y|X) = \sqrt{\frac{\int \int (F_{Y|X}(y|x) - F_Y(y))^2 dF_X(x) dF_Y(y)}{\int F_Y(y)(1 - F_Y(y)) dF_Y(y)}}.$$

It can be easily seen that both  $\omega_k$  and  $\bar{\omega}_k$  depend on  $F_Y$  except only for the case  $Y$  is a continuous random variable. In this case, we can use the change of variable formula to nullify the effect of  $F_Y$ . Also,

$$\bar{\omega}_k(Y|X) \neq \left[ \frac{\int \int |F_{Y|X}(y|x) - F_Y(y)|^k dF_X(x) dF_Y(y)}{\omega_k^k(Y|Y) - \bar{\omega}_k(Y)} \right]^{\frac{1}{k}}$$

in general.